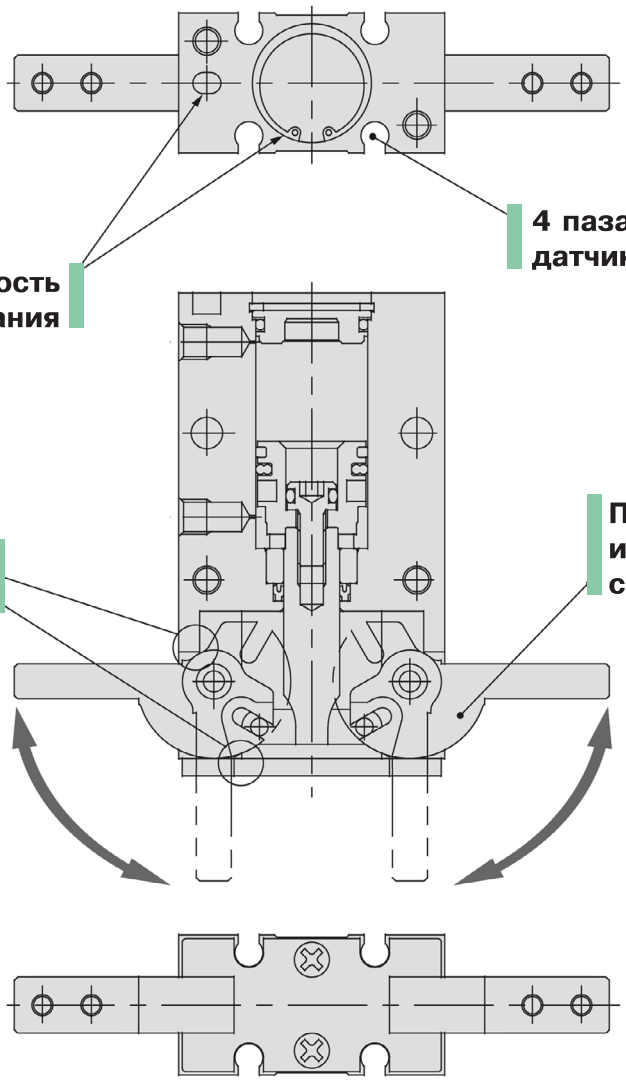
Пневматический захват серия MHY2

Двухпальцевый захват с расположением рабочих органов под углом 180°



4 паза для монтажа датчиков положения

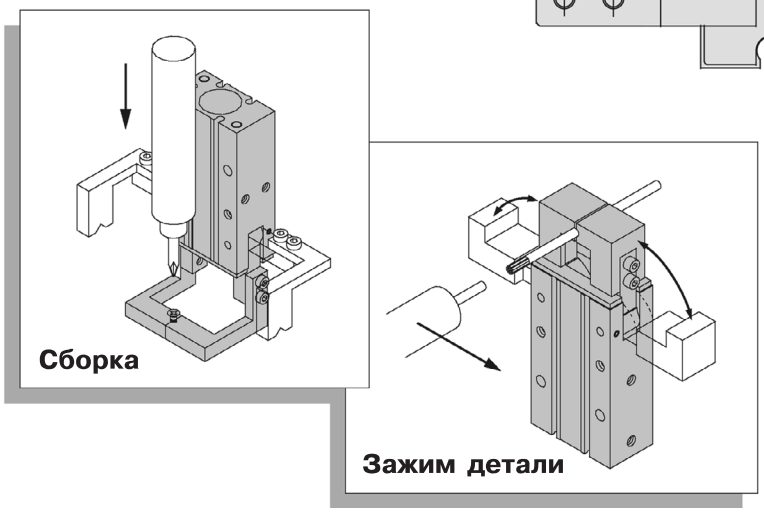
Высокая точность позиционирования

Повышенная защита от внешнего загрязнения

Зазоры минимизированы

Пальцы из нержавеющей стали

Примеры использования:



Пневматический захват с углом раскрытия 180°

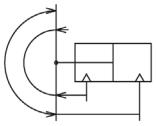
MHY2

ø10~25

Технические характеристики

Тип	2-пальцевый захват с углом раскрытия 180°
Принцип действия	Двустороннего действия
Среда	Очищенный сжатый воздух, с содержанием масла или без него
Рабочее давление (МПа)	0.1~0.6
Рабочая температура (°C)	от –10 до +60
Точность позиционирования (мм)	±0.2
Присоединительная резьба	M5
Макс. частота срабатывания (цикл/мин)	60

Тип	MHY2-10D	MHY2-16D	MHY2-20D	MHY2-25D
Диам. поршня, мм	10	16	20	25
Эфф. удерживающий момент (Н/м) при 0.5 (МПа)*	0.16	0.54	1.1	2.28
Угол раскрытия	-3°~180°			
Вес (г)**	70	150	320	560



* Эффективный удерживающий момент приводится для средней точки рычага L на одном пальце. Более точные значения см. на диаграммах (стр. 2-173).

**Вес захватов указан без учета датчиков положения.

Номер для заказа

ø поршня (мм)	Номер для заказа
10	**MHY2-10D**
16	**MHY2-16D**
20	**MHY2-20D**
25	**MHY2-25D**

Объем поставки

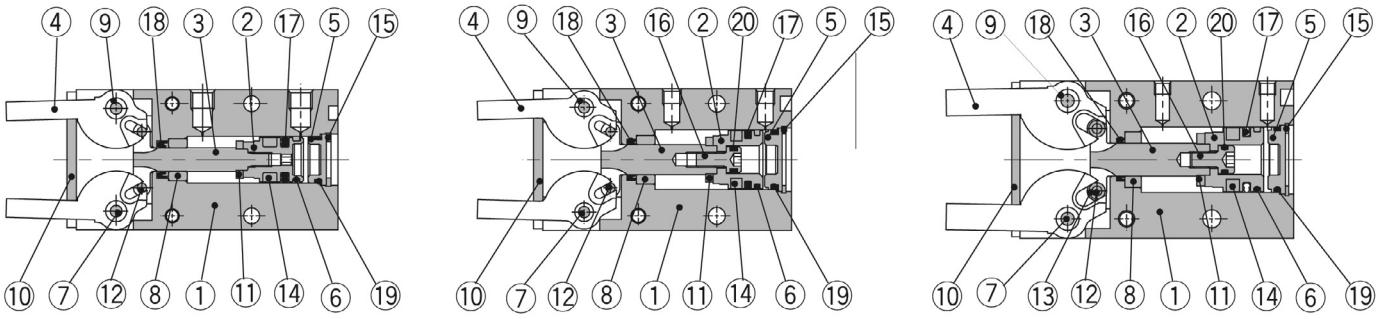
Захват поставляется без крепежных элементов и датчиков положения. Датчики положения D-M9PL, D-M9PVL, D-M9BL, D-M9BVL заказываются отдельно (см. стр. 2-220)

Пневматический захват с углом раскрытия 180°
MHY2

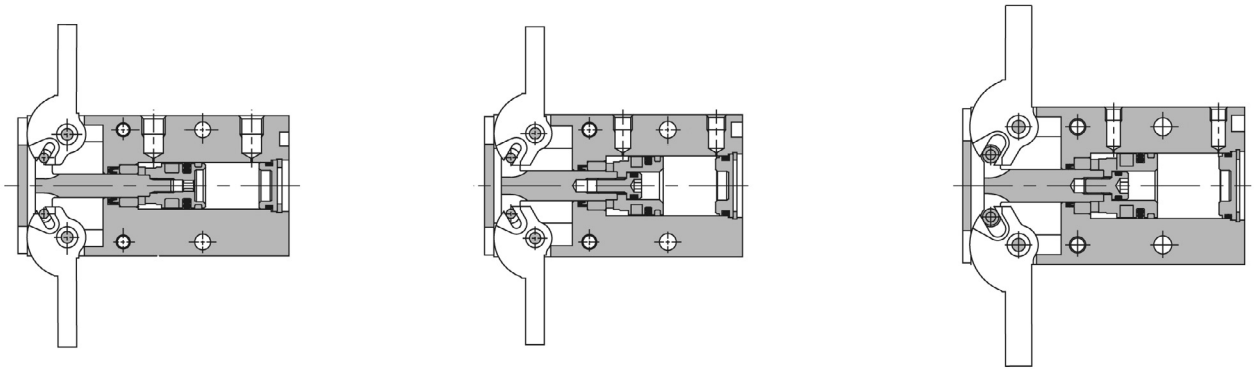
Конструкция

ø 10 **ø 16** **ø 20, ø 25**

Положение: **захват закрыт**



Положение: **захват раскрыт**



Спецификация

Поз	Обозначение	Материал	Примечание
1	Корпус	Алюминий	Анодирование
2	Поршень	ø10: нерж. сталь ø16-ø25: алюминий	ø16-ø25: хромирование
3	Клин	Нерж. сталь	Термообработка
4	Палец	Нерж. сталь	Термообработка
5	Крышка	Полимер	
6	Кольцо	Полимер	
7	Ось	Нерж. сталь	Азотирование
8	Подшипник A	Сталь	
9	Подшипник B	Алюм. сплав	
10	Концевая плита	Нерж. сталь	
11	Демпфер	Полиуретан	
12	Ролик	Подшипниковая сталь	
13	Ролик	Высокоуглеродистая сталь	Азотирование
14	Магнит		
15	Стопорное кольцо	Сталь	Никелирование
16	Винт	Нерж. сталь	
17,18 19,20	Уплотнения (ремкомплект)	NBR	

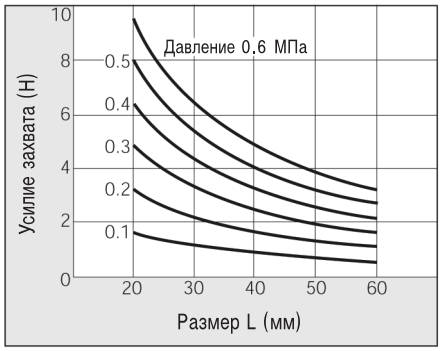
Ремкомплект

Состоит из поз. 17-20

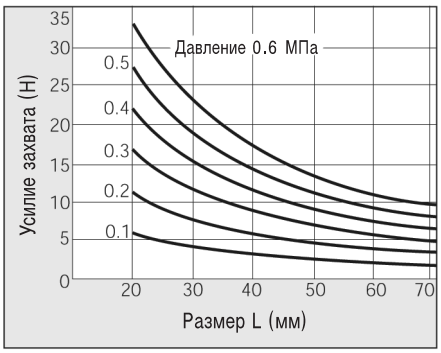
Тип	Номер для заказа
MHY2-10D	**MHY10-PS**
MHY2-16D	**MHY16-PS**
MHY2-20D	**MHY20-PS**
MHY2-25D	**MHY25-PS**

Усилие захвата

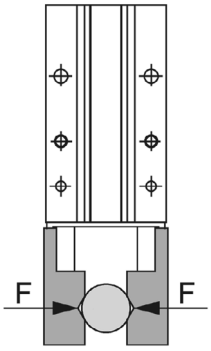
MHY2-10D



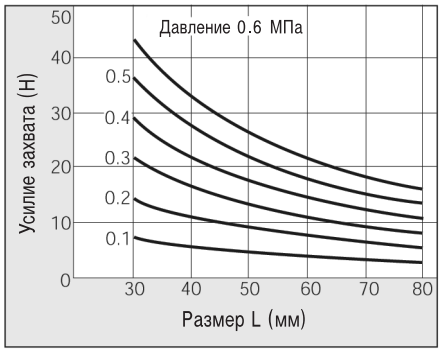
MHY2-16D



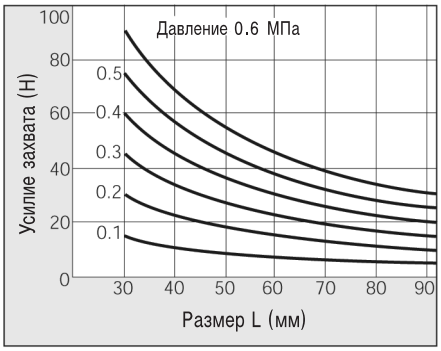
Размер L

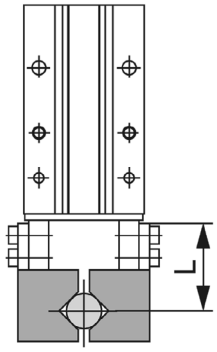


MHY2-20D

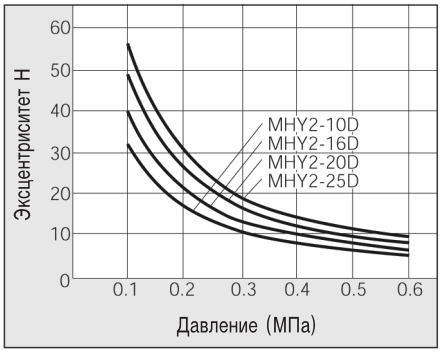


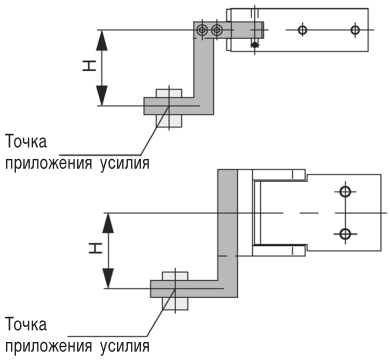
MHY2-25D





Эксцентрическое приложение усилия





Критерии выбора

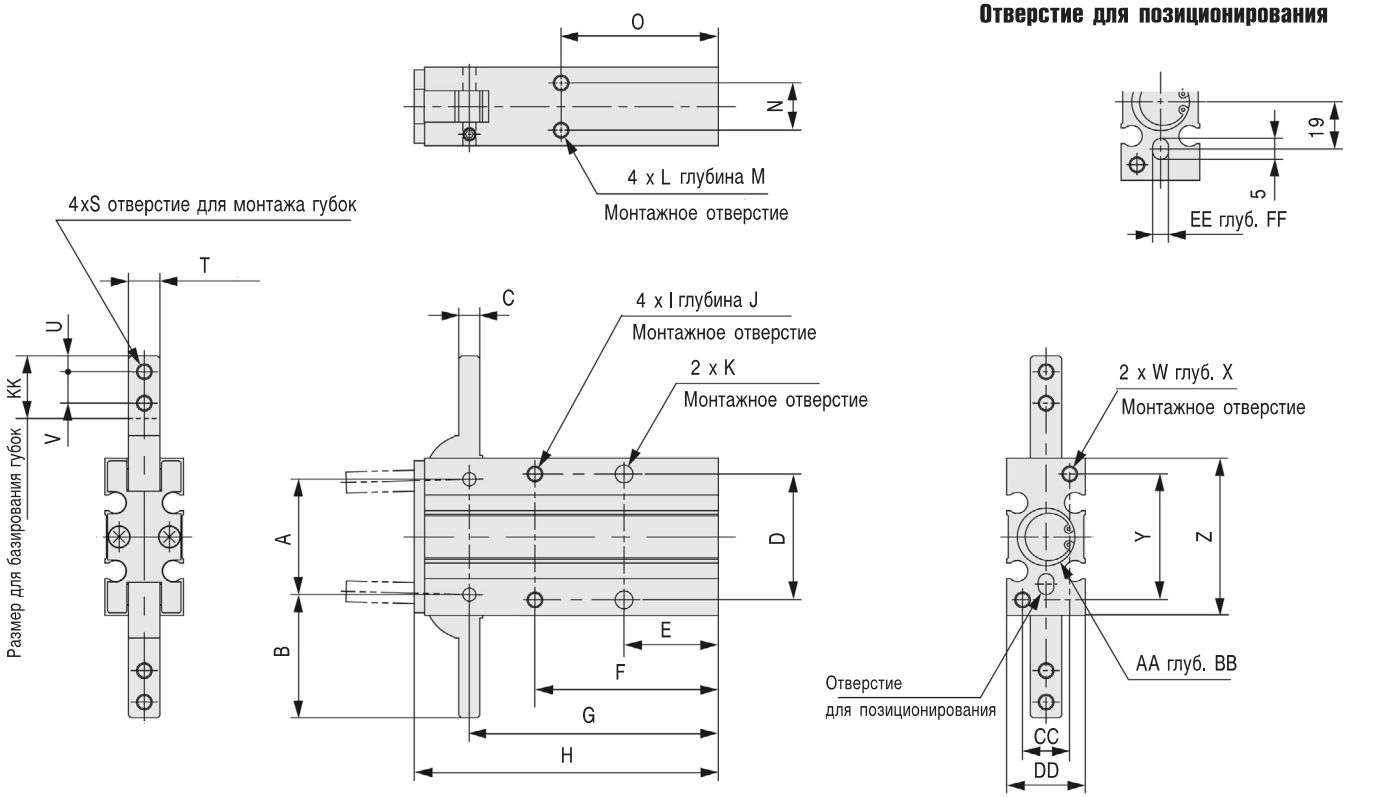
Выбор надлежащей модели
должен осуществляться на основании следующих критериев:

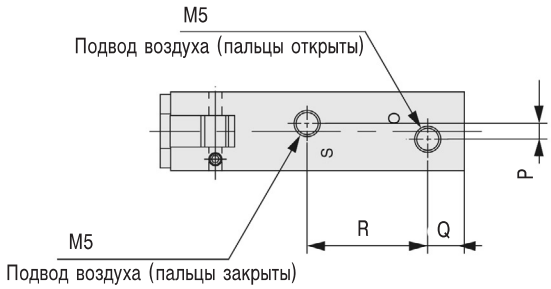
- Вес манипулируемых деталей
- Коэффициент трения между захватом и деталью
- Пространственная компоновка деталей

Рекомендуется выбрать захват
таким образом, чтобы усилие захвата было в 10-20 раз больше веса детали

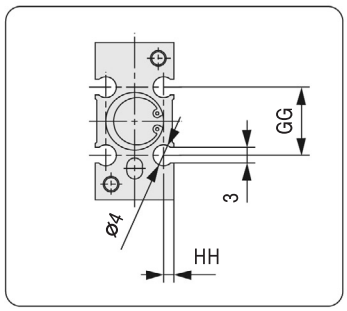
Пневматический захват с углом раскрытия 180°
MHY2

Размеры





Паз для монтажа датчиков положения



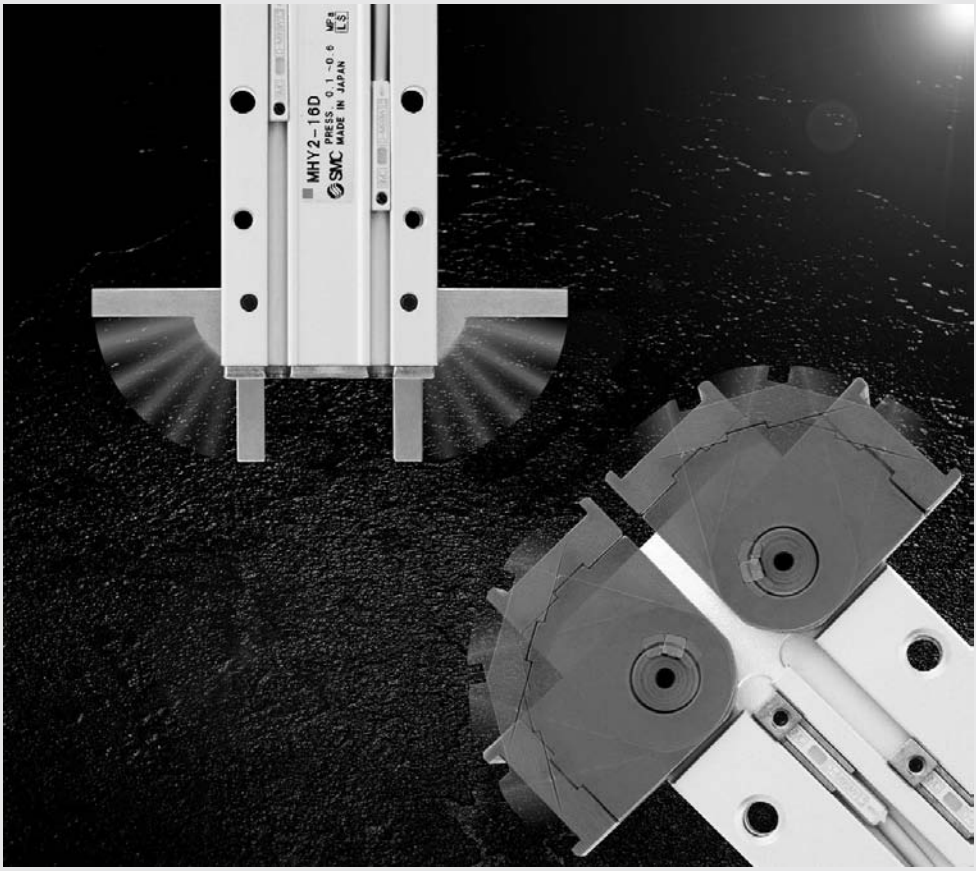
Тип	A	B	C	D	E	F	G	H	I	J	ØK	L	M	N	O	P	Q
MHY2-10	22	23.5	4	24	18	35	47.5	58	M3	6	3.4	M3	4	9	30	3	7
MHY2-16	28	28.5	5	30	20	41	55.5	69	M4	8	4.5	M4	5	12	33	8	7
MHY2-20	36	37	8	36	25	50	69	86	M5	10	5.5	M5	8	14	42	12	8
MHY2-25	45	45	10	42	30	60	86	107	M6	12	6.6	M6	10	16	50	14	8

R	S	T	U	V	W	X	Y	Z	AA	BB	CC	DD	EE	FF	GG	HH	II	JJ	KK
23	M3	6	3	6	M3	6	24	30	11H9	1.5	9	15	3H9	3	13	2	4	9	12
25	M3	8	4	7	M4	8	30	38	17H9	1.5	12	20	3H9	3	18	2.5	4	15	14
32	M4	10	5	9	M5	10	38	48	21H9	1.5	16	26	4H9	4	20	3	5	19	18
42	M5	12	6	12	M6	12	46	58	26H9	1.5	18	30	4H9	4	24	3	5	23	225

180° Angular Style Air Gripper

Series MHY2/MHW2

Cam Style / Rack & Pinion Style



180° Angular Style Air Gripper

Cam Style Rack & Pinion Style

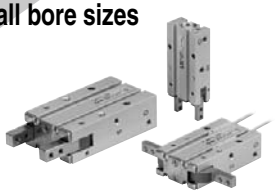
Series MHY2/MHW2

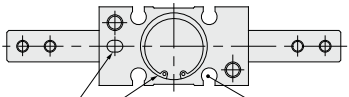
Series MHY2/Cam Style

Light and compact size in small bore sizes

Model	Bore size (mm)	Gripping moment* (N·m)	Over length L (mm)	Weight (g)
MHY2-10D	10	0.16	71	70
MHY2-16D	16	0.54	84	150
MHY2-20D	20	1.10	106	320
MHY2-25D	25	2.28	131	560

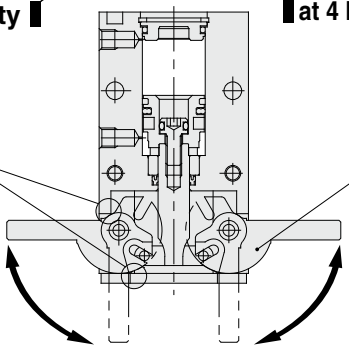
* At the pressure of 0.5 MPa





Auto switch mounting at 4 locations

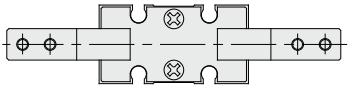
Improved mounting repeatability

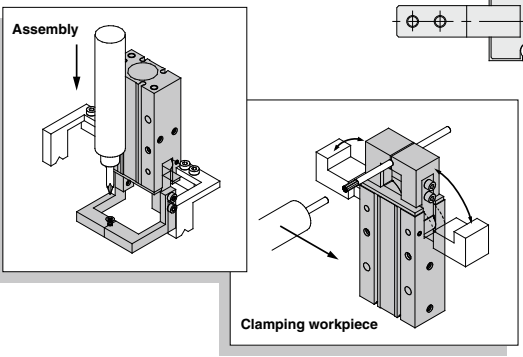


Stainless steel fingers are standard.

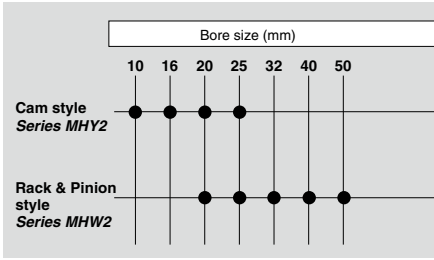
Resistance to dusty environments

Reduced opening sizes helps prevent foreign objects from entering.





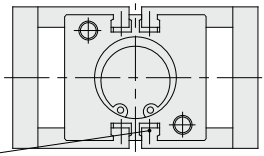
Series Variations



SMC

Series MHW2/Rack & Pinion Style

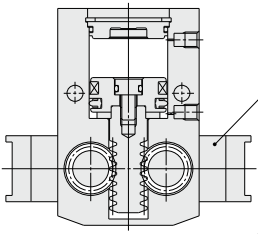
Unique seal design allows shorter total length construction and constant grippng force when opening and closing fingers. (PAT.PEND)



Auto switch mounting at 4 locations

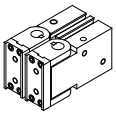
Model	Bore size (mm)	Gripping moment * (N·m)	Over length L(mm)	Weight (g)
MHW2-20D	20	0.30	68	300
MHW2-25D	25	0.73	78	510
MHW2-32D	32	1.61	93.5	905
MHW2-40D	40	3.70	117.5	2135
MHW2-50D	50	8.27	154	5100

* At the pressure of 0.5 MPa

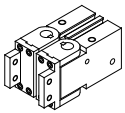


Two finger styles available.

Flat finger type



Right angle finger type

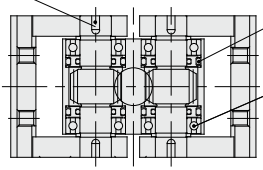


Key connection is ideal for impact resistance.

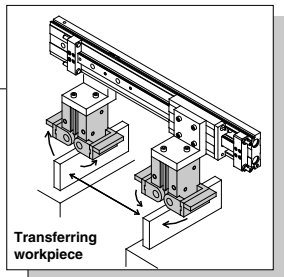
Key connection between finger and shaft prevents finger angle slippage during impact.

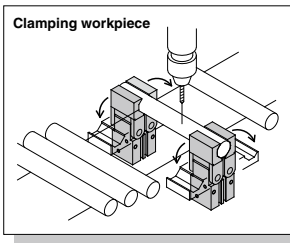
Dustproof construction

Seal arrangement protects gripper from harsh dusty environments.



Bearings are standard.





INDEX

Model Selection

Model Selection

Selection Procedure

Step 1 Confirmation of gripping force → **Step 2** Confirmation of gripping point → **Step 3** Confirmation of moment of inertia of attachments

Step 1 Confirmation of Gripping Force

Confirmation of conditions → Calculation of required gripping force → Selection of model from gripping force graph

Example

Workpiece mass: 0.05 kg

Guidelines for the selection of the gripper with respect to workpiece mass

- Although conditions differ according to the workpiece shape and the coefficient of friction between the attachments and the workpiece, select a model that can provide a gripping force of 10 to 20 times the workpiece mass, or more.
- If high acceleration, deceleration or impact forces are encountered during motion, a further margin of safety should be considered.

Example) For setting the gripping force to be at least 20 times the work weight;

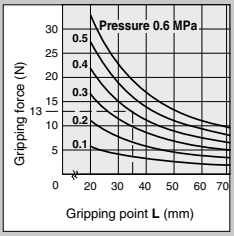
Required gripping force

= 0.05 kg x 20 x 9.8 $^{m}/_{s^2}$ = 10 N min.

Gripping point **L** = 35 mm

Operating pressure: 0.4 MPa

MHY2-16D



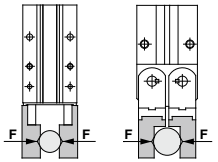
- When **MHY2-16D** is selected, the gripping force is determined to be 13 N according to the gripping point distance (L = 35 mm) and the pressure (0.4 MPa).
- The gripping force is 26 times the workpiece mass and therefore satisfies a gripping force setting value of 20 times or more.

Effective Gripping Force

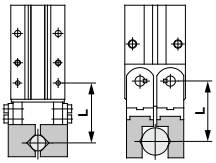
Series MHY2/MHW2 Double Acting

- Indication of effective grippng force

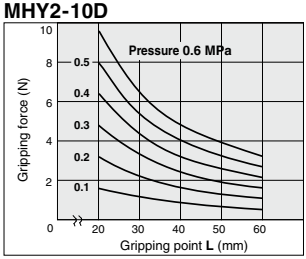
  The effective gripping force shown in the graphs to the right is expressed as F, which is the impellent force of one finger, when both fingers and attachments are in full contact with the workpiece as shown in the figure below.



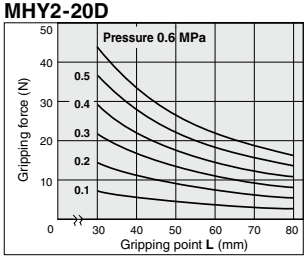
External grip



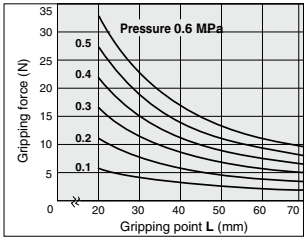
MHY2-10D



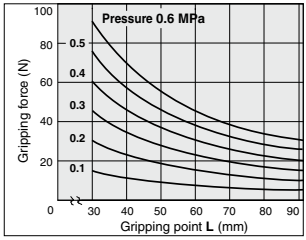
MHY2-20D



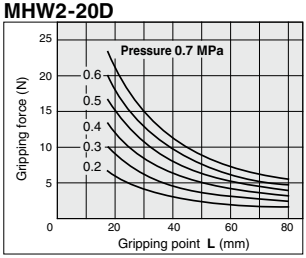
MHY2-16D



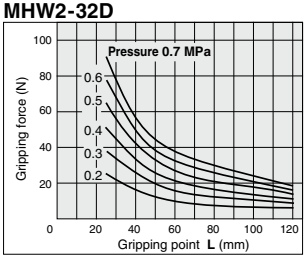
MHY2-25D



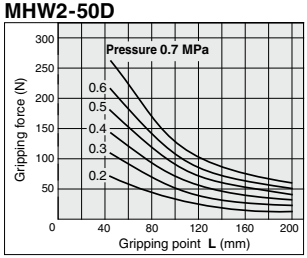
MHW2-20D



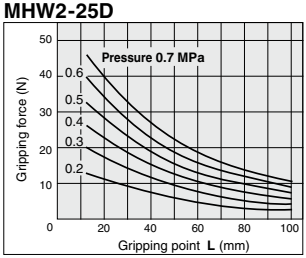
MHW2-32D



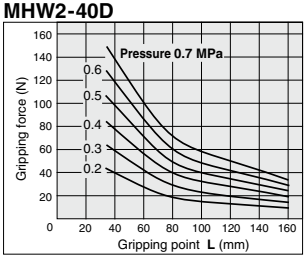
MHW2-50D



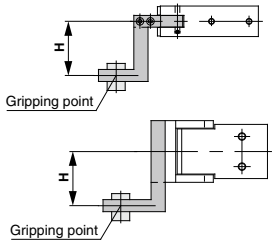
MHW2-25D



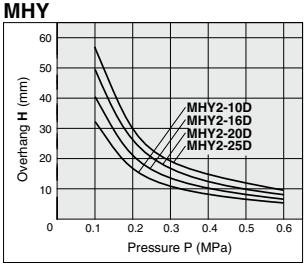
MHW2-40D



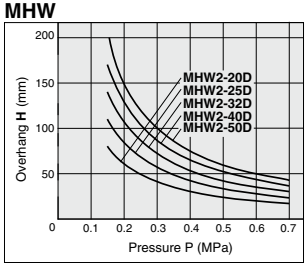
Step 2 Confirmation of Gripping Point



MHY



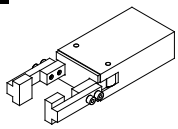
MHW



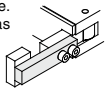
- Workpiece should be held at a point within the range of overhanging distance (H) for a given pressure indicated in the tables on the right.
- When the workpiece is held at a point outside of the recommended range for a given pressure, it may cause adverse effect on the product life.

Model Selection

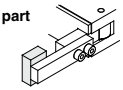
Step 3 Confirmation of Moment of Inertia of Attachments



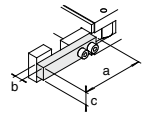
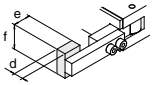
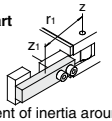
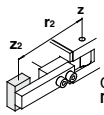
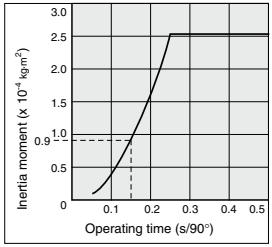
Confirm the moment of inertia for the attachment at one side. Calculate the moment of inertia for A and B separately as shown in the figures on the right.



A part



B part

Procedure	Calculation	Calculation example
1. Check the operating conditions, dimensions of attachment, etc.	**A part**  **B part**  	Operating model: MHY2-16D Opening time: 0.15 s **a** = 40 (mm) **b** = 7 (mm) **c** = 8 (mm) **d** = 5 (mm) **e** = 10 (mm) **f** = 12 (mm)
2. Calculate the moment of inertia of attachment.	**A part**  Calculation of weight m_1 = a x b x c x Specific gravity Moment of inertia around Z_1 axis $I_{Z1} = \{m_1(a^2 + b^2)/12\} \times \frac{10^{-6}}{*}$ Moment of inertia around Z axis $I_A = I_{Z1} + m_1 r_1^2 \times \frac{10^{-6}}{*}$ **B part**  Calculation of weight m_2 = d x e x f x Specific gravity Moment of inertia around Z_2 axis $I_{Z2} = \{m_2(d^2 + e^2)/12\} \times \frac{10^{-6}}{*}$ Moment of inertia around Z axis $I_B = I_{Z2} + m_2 r_2^2 \times \frac{10^{-6}}{*}$ Total moment of inertia $I = I_A + I_B$ (* Constant for unit conversion)	Material of attachment: Aluminum alloy (Specific gravity = 2.7) r_1 = 37 (mm) m_1 = 40 x 7 x 8 x 2.7 x 10^{-6} = 0.006 (kg) I_{Z1} = {0.006 x (40^2 + 7^2)/12} x 10^{-6} = 0.8 x 10^{-6} (kg·m^2) I_A = 0.8 x 10^{-6} + 0.006 x 37^2 x 10^{-6} = 9.0 x 10^{-6} (kg·m^2) r_2 = 47(mm) m_2 = 5 x 10 x 12 x 2.7 x 10^{-6} = 0.002 (kg) I_{Z2} = {0.002 x (5^2 + 10^2)/12} x 10^{-6} = 0.02 x 10^{-6} (kg·m^2) I_B = 0.02 x 10^{-6} + 0.002 x 47^2 x 10^{-6} = 4.4 x 10^{-6} (kg·m^2) I = 9.0 x 10^{-6} + 4.4 x 10^{-6} = 13.4 x 10^{-6}= 0.13 x 10^{-4} (kg·m^2)
3. Determine the allowable moment of inertia from the graph.	**MHY2-16D**  	The moment of inertia is determined to be 0.9 x 10^{-4} (kg·m^2) according to the operating time (0.15 s) from the graph to the left.
4. Confirm the moment of inertia of one attachment is within the allowable range.	Moment of inertia of attachment < Allowable moment of inertia	0.13 x 10^{-4} (kg·m^2) < 0.9 x 10^{-4} (kg·m^2) Possible to use this model MHY2-16D completely.

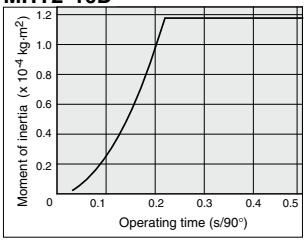
Symbol

Symbol	Definition	Unit
Z	Finger rotation axis	—
Z_1	Axis on the center gravity of A part of attachment and parallel to Z	—
Z_2	Axis on the center gravity of B part of attachment and parallel to Z	—
I	Total moment of inertia for attachment	kg·m²
I_{Z1}	Inertia moment around the Z_1 axis of A part of attachment	kg·m²
I_{Z2}	Inertia moment around the Z_2 axis of B part of attachment	kg·m²

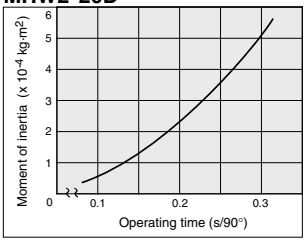
Symbol	Definition	Unit
I_A	Moment of inertia around the Z axis of A part of attachment	kg·m²
I_B	Moment of inertia around the Z axis of B part of attachment	kg·m²
m_1	Weight of A part of attachment	kg
m_2	Weight of B part of attachment	kg
r_1	Distance between Z and Z1 axis	mm
r_2	Distance between Z and Z2 axis	mm

Allowable Range of Moment of Inertia of Attachment

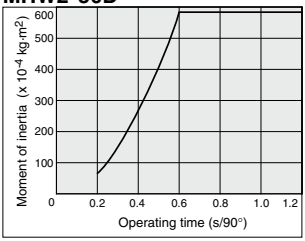
MHY2-10D



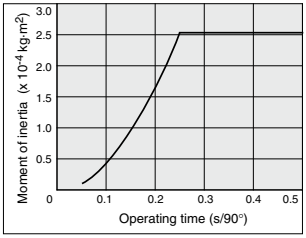
MHW2-20D



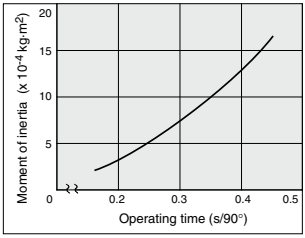
MHW2-50D



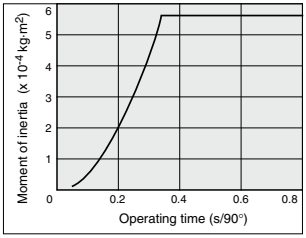
MHY2-16D



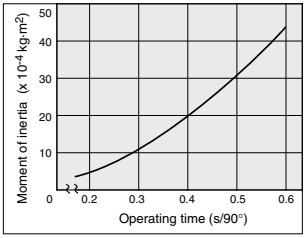
MHW2-25D



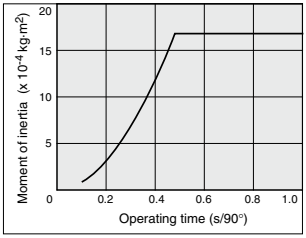
MHY2-20D



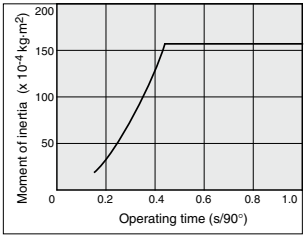
MHW2-32D



MHY2-25D



MHW2-40D



180° Angular Style Air Gripper
Rack & Pinion Style
Series MHW2
ø20, ø25, ø32, ø40, ø50

How to Order

MHW2 – 20 □ D 1 – M9BW □ – □

Number of fingers

2	2 fingers

Bore size

20	20 mm
25	25 mm
32	32 mm
40	40 mm
50	50 mm

Port thread type

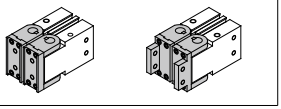
Symbol	Type	Size
Nil	M thread	ø20, ø25
	Rc	ø32
TN	NPT	ø40
TF	G	ø50

Action

D	Double acting

Finger option

Nil: Flat type fingers (Standard) **1**: Right angle type fingers tapped mounting



Auto switch

Nil	Without auto switch (Built-in magnet)

∗For the applicable auto switch model, refer to the table below.

Number of auto switches

Nil	2 pcs.
S	1 pc.
n	n pc.

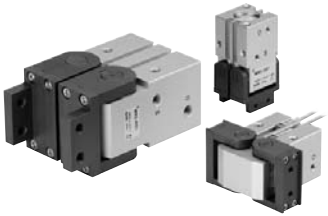
Made to Order
Refer to page 714 for details.

Applicable Auto Switches
/ Refer to pages 807 to 856 for further information on auto switches.

Type	Special function	Electrical entry	Indicator light	Wiring (Output)	Load voltage DC	Load voltage AC	Auto switch model: Electrical entry direction Perpendicular	Auto switch model: Electrical entry direction In-line	Lead wire length (m)∗ 0.5 (Nil)	1 (M)	3 (L)	5 (Z)	Pre-wired connector	Applicable load	
Solid state auto switch	——	Grommet	Yes	3-wire(NPN)	5 V, 12 V	—	**M9NV**	**M9N**	●	●	●	○	○	IC circuit	Relay, PLC
				3-wire(PNP)			**M9PV**	**M9P**	●	●	●	○	○		
				2-wire	12 V		**M9BV**	**M9B**	●	●	●	○	○	—	
	Diagnosis (2-color indication)			3-wire(NPN)	5 V, 12 V		**M9NWV**	**M9NW**	●	●	●	○	○	IC circuit	
				3-wire(PNP)			**M9PWV**	**M9PW**	●	●	●	○	○		
				2-wire	12 V		**M9BWV**	**M9BW**	●	●	●	○	○	—	
	Water resistant (2-color indication)			3-wire(NPN)	5 V, 12 V		**M9NAV**∗∗	**M9NA**∗∗	○	○	●	○	○	IC circuit	
				3-wire(PNP)			**M9PAV**∗∗	**M9PA**∗∗	○	○	●	○	○		
				2-wire	12 V		**M9BAV**∗∗	**M9BA**∗∗	○	○	●	○	○	—	

∗∗ Water resistant type auto switches can be mounted on the above models, but in such case SMC cannot guarantee water resistance.
∗ Lead wire length symbols: 0.5 m ····· Nil (Example) M9NW
1 m ····· M (Example) M9NWM
3 m ····· L (Example) M9NWL
5 m ····· Z (Example) M9NWZ
∗ Auto switches marked with a "○" symbol are produced upon receipt of order.

Note 1) When using the 2-color indicator type, please make the setting so that the indicator is lit in red to ensure the detection at the proper position of the air gripper.
Note 2) When ordering the air gripper with the auto switch, the auto switch mounting bracket is included.
When ordering the auto switch separately, the auto switch mounting bracket (BMG2-012) is required.



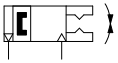
Specifications

Fluid	Air
Operating pressure	0.15 to 0.7 MPa
Ambient and fluid temperature	–10 to 60°C
Repeatability	±0.2 mm
Max. operating frequency	ø20, 25: 60 c.p.m. ø32 to 50: 30 c.p.m.
Lubrication	Not required
Action	Double acting
Auto switch (Option) Note)	Solid state auto switch (3-wire, 2-wire)

Note) Refer to pages 807 to 856 for further information on auto switches.

Symbol

Double acting: External grip



Model

Model	Bore size (mm)	Effective gripping force (N·m)	Opening angle (Both sides)		Weight (2) (g)
			Opening	Closing	
MHW2-20D	20	0.30	180°	–5°	300
MHW2-20D1					320
MHW2-25D	25	0.73		–6°	510
MHW2-25D1					540
MHW2-32D	32	1.61		–5°	910
MHW2-32D1					950
MHW2-40D	40	3.70		–5°	2140
MHW2-40D1					2270
MHW2-50D	50	8.27		–4°	5100
MHW2-50D1					5350

Note 1) At the pressure of 0.5 MPa
Note 2) Except auto switch

- Refer to "How to Select the Applicable Model" on page 702
- Refer to pages 702 and 703 for the details on effective holding force and allowable overhanging distance.

Made to Order

Made to Order
(Refer to pages 727 to 759 for the details.)

Symbol	Specifications/Description
-X4	Heat resistance
-X5	Fluororubber seal
-X50	Without magnet
-X53	EPDM for seals, Fluorine grease
-X63	Fluorine grease
-X79	Grease for food processing machines, Fluorine grease
-X79A	Grease for food processing machines

⚠ Precautions

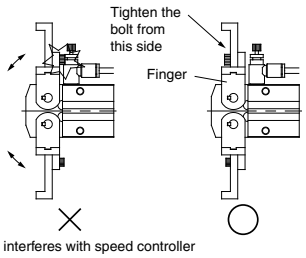
Be sure to read before handling.
Refer to front matter 35 for Safety Instructions and pages 402 to 410 for Air Gripper and Auto Switch Precautions.

Mounting

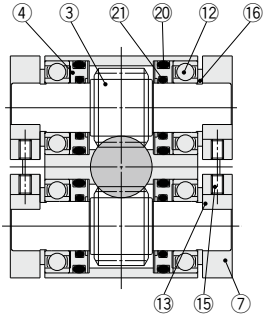
MHW

⚠ Warning

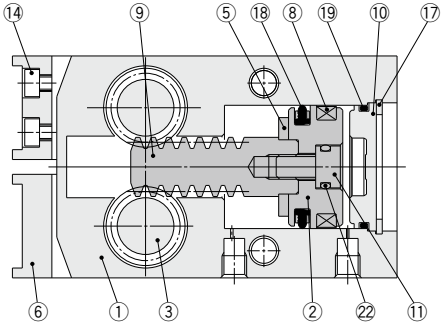
When using right angle finger tap mounting type, monitor the interference of the bolt with the speed controller.



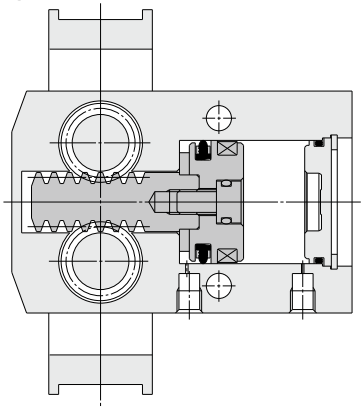
Construction



Closed condition



Open condition



Component Parts

No.	Description	Material	Note
1	**Body**	Aluminum alloy	Hard anodized
2	**Piston**	Aluminum alloy	Hard anodized
3	**Pinion gear**	Carbon steel	Heat treated
4	**Seal cover**	Brass	
5	**Bumper**	Urethane rubber	
6	**Finger (A)**	Carbon steel	Nitriding
7	**Finger (B)**	Carbon steel	Nitriding
8	**Rubber magnet**	Synthetic rubber	
9	**Rack**	Carbon steel	Nitriding

No.	Description	Material	Note
10	**Cap**	ø20, 25: Resin	
		ø32 to 50: Aluminum alloy	Hard anodized
11	**Piston bolt**	Stainless steel	
12	**Ball bearing**	Carbon steel	Schield type
13	**Key**	Carbon steel	
14	**Hexagon socket head bolt**	Carbon steel	Zinc chromated
15	**Hexagon socket cap screw**	Carbon steel	Zinc chromated
16	**Type C retaining ring**	Carbon steel	Phosphate coated
17	**Type C retaining ring**	Carbon steel	Phosphate coated

Replacement Parts

Description		MHW2-20	MHW2-25	MHW2-32	MHW2-40	MHW2-50	Main parts
Seal kit		MHW20-PS	MHW25-PS	MHW32-PS	MHW40-PS	MHW50-PS	⑱⑲⑳㉑㉒
Piston assembly		MHW-A2001	MHW-A2501	MHW-A3201	MHW-A4001	MHW-A5001	②⑤⑧⑨⑪㉒
Finger assembly	MHW2-□D	MHW-A2002	MHW-A2502	MHW-A3202	MHW-A4002	MHW-A5002	⑥⑦⑬⑭⑮
	MHW2-□D1	MHW-A2002-1	MHW-A2502-1	MHW-A3202-1	MHW-A4002-1	MHW-A5002-1	
Finger A assembly	MHW2-□D	MHW-A2006	MHW-A2506	MHW-A3206	MHW-A4006	MHW-A5006	⑥⑭
Finger C assembly	MHW2-□D1	MHW-A2006-1	MHW-A2506-1	MHW-A3206-1	MHW-A4006-1	MHW-A5006-1	⑥⑭
Finger B assembly		MHW-A2007	MHW-A2507	MHW-A3207	MHW-A4007	MHW-A5007	⑦⑬⑮

∗ Please order 1 piece finger assembly per one unit.

Replacement part/grease pack part no. :

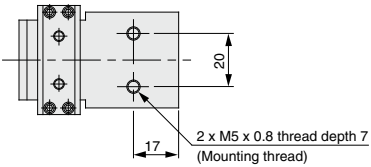
ø20, ø25, ø32 : GR-S-010(10g)

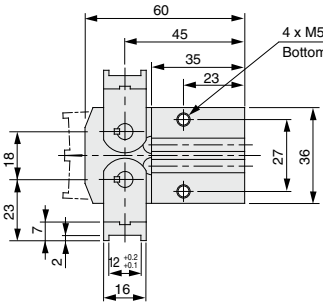
ø40, 50 : GR-S-020(20g)

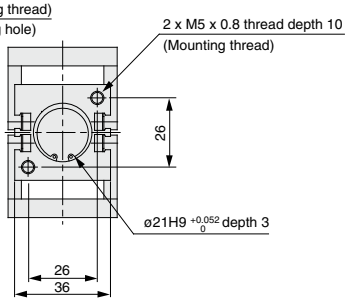
Dimensions

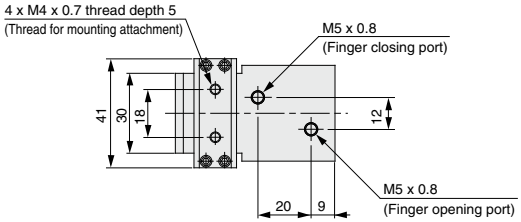
MHW2-20D

Flat finger type (Standard)

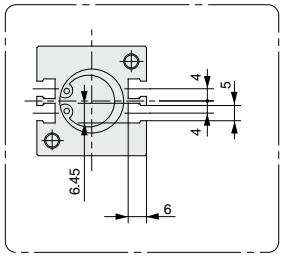






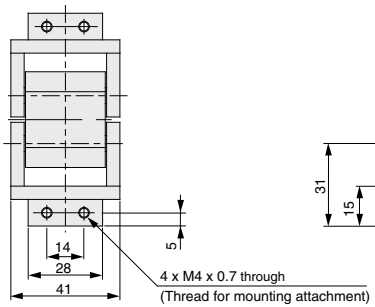


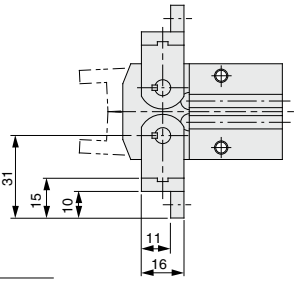
Auto Switch Mounting Groove Dimensions



MHW2-20D1

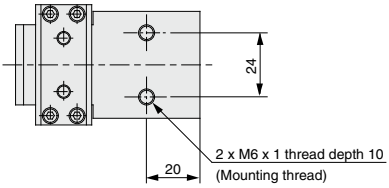
Right angle finger type

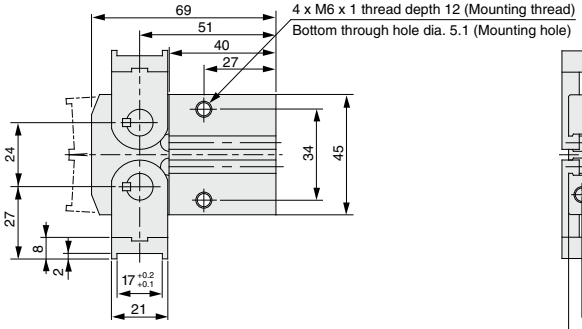


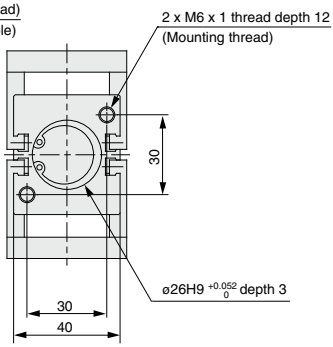


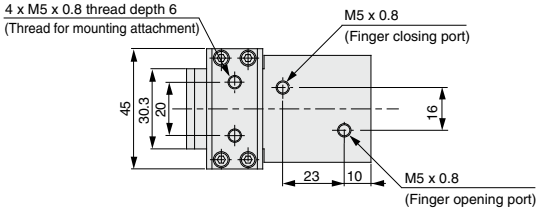
Dimensions

MHW2-25D
Flat finger type (Standard)

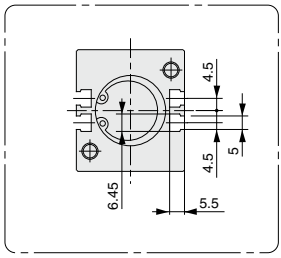




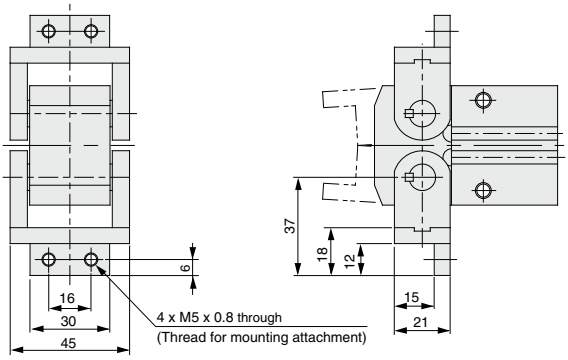




Auto Switch Mounting Groove Dimensions



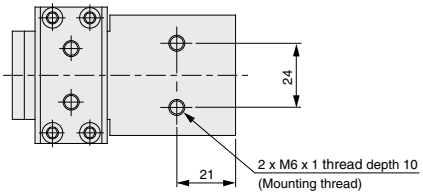
MHW2-25D1
Right angle finger type

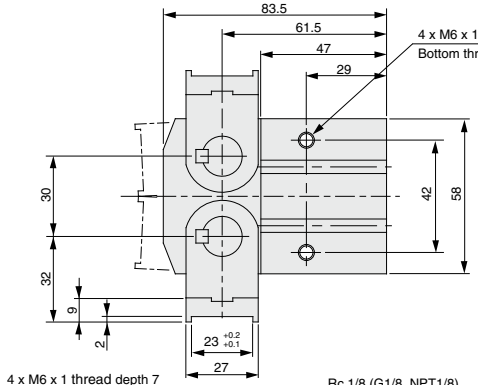


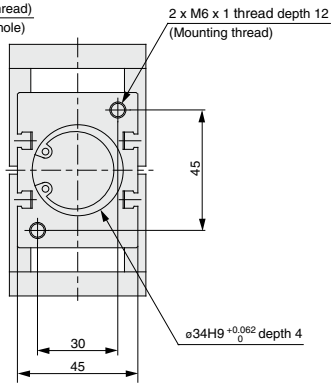
Dimensions

MHW2-32D

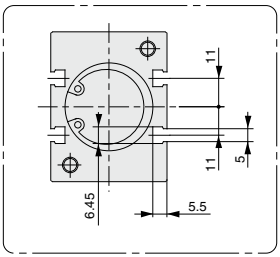
Flat finger type (Standard)





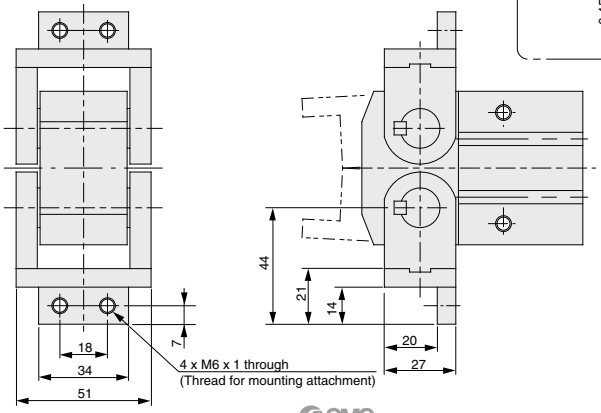


Auto Switch Mounting Groove Dimensions



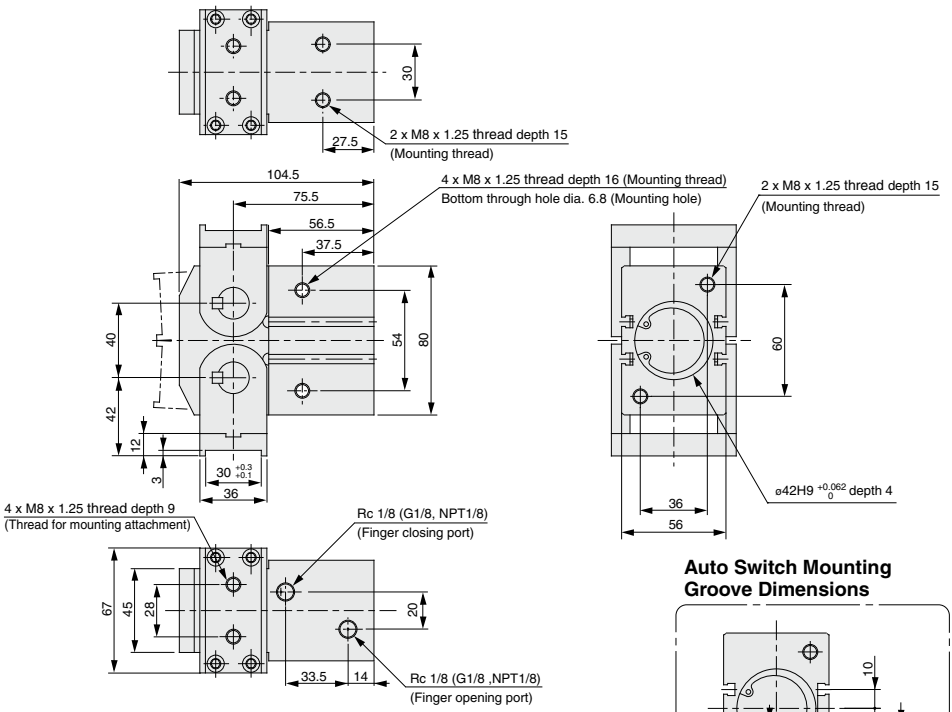
MHW2-32D1

Right angle finger type

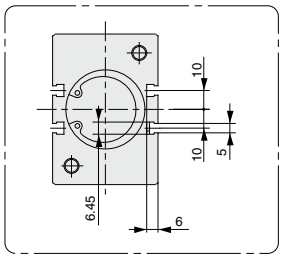


Dimensions

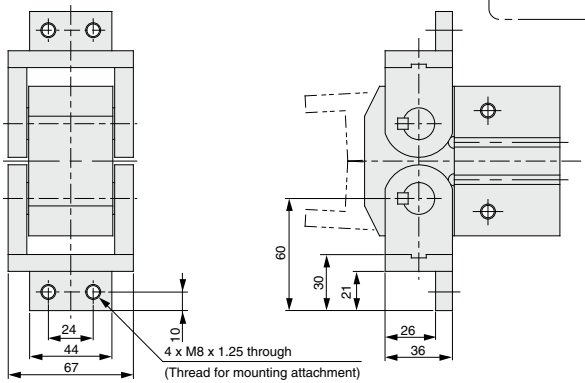
MHW2-40D
Flat finger type (Standard)



Auto Switch Mounting Groove Dimensions



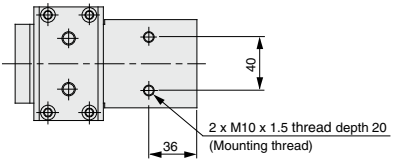
MHW2-40D1
Right angle finger type

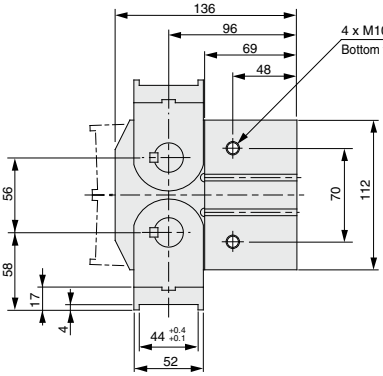


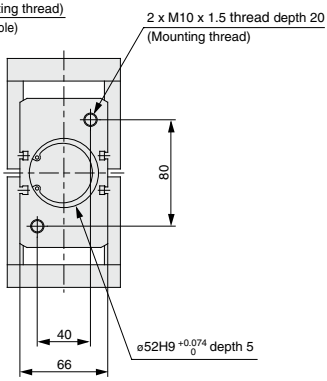
Dimensions

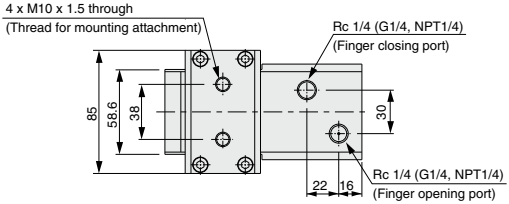
MHW2-50D

Flat finger type (Standard)

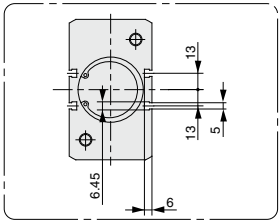






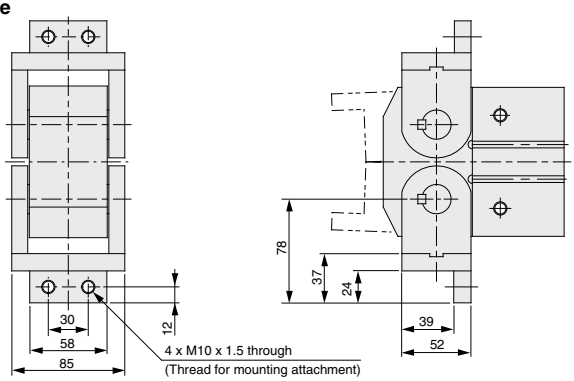


Auto Switch Mounting Groove Dimensions



MHW2-50D1

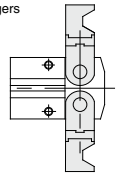
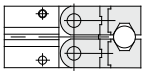
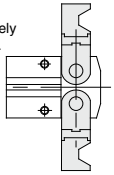
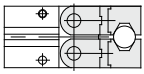
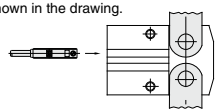
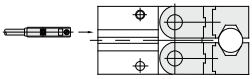
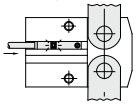
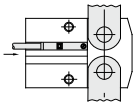
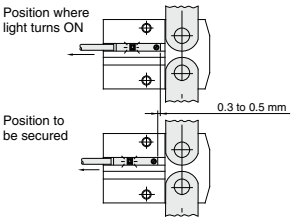
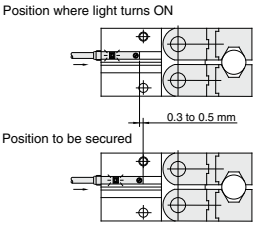
Right angle finger type



Series *MHY2/MHW2*
Auto Switch Installation Examples and Mounting Positions

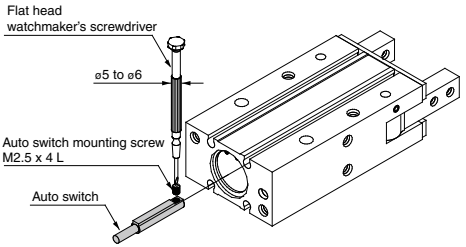
Various auto switch applications are possible through different combinations of auto switch quantities and detecting positions.

Detection when Gripping Exterior of Workpiece

Detection example	1. Confirmation of the fingers in reset position	2. Confirmation of work held
Position to be detected	Position of fingers fully opened 	Position when gripping a workpiece 
Operation of auto switch	Auto Switch turned ON when fingers return. (Light ON)	Auto Switch turned ON when gripping a workpiece. (Light ON)
How to determine auto switch installation position At no pressure or low pressure, connect the auto switch to a power supply, and follow the directions.	Step 1) Completely open the fingers. 	Step 1) Position fingers for gripping a workpiece. 
	Step 2) Insert the auto switch into the switch groove in the direction shown in the drawing. 	Step 2) Insert the auto switch into the switch groove in the direction shown in the drawing. 
	Step 3) Slide the auto switch in the direction of the arrow until the indicator light illuminates.  Step 4) Slide the auto switch further in the direction of the arrow until the indicator light goes out.  Step 5) Move the auto switch in the opposite direction and fasten it at a position 0.3 to 0.5 mm beyond the position where the indicator light illuminates. 	Step 3) Slide the auto switch in the direction of the arrow until the indicator light illuminates. Move the switch an additional 0.3 to 0.5 mm in the direction of the arrow and fasten it. 

Auto Switch Mounting

To set the auto switch, insert the auto switch into the installation groove of the gripper from the direction indicated in the following drawing. After setting the position, tighten the attached auto switch mounting set screw with a flat head watchmaker's screwdriver.

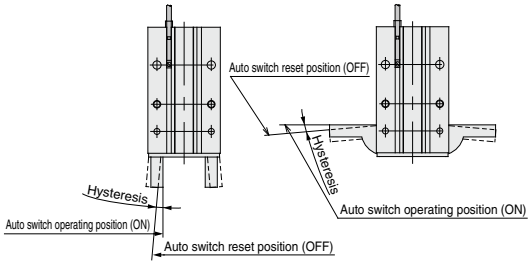


Note) Use a watchmaker's screwdriver with a grip diameter of 5 to 6 mm to tighten the auto switch mounting screw.
The tightening torque should be about 0.05 to 0.15 N·m.

∗ Refer to the page 814 for the details on "Auto Switches Connection and Example".

Auto Switch Hysteresis

Auto switches have hysteresis similar to micro switches. Use the table below as a guide when adjusting auto switch positions, etc.

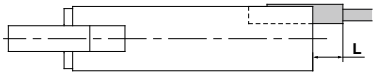


		D-M9□(V) D-M9□W(V)/M9A(V)
MHY2 -10D	Finger fully closed	2°
	Finger fully open	4°
MHY2 -16D	Finger fully closed	2°
	Finger fully open	3°
MHY2 -20D	Finger fully closed	2°
	Finger fully open	3°
MHY2 -25D	Finger fully closed	1°
	Finger fully open	2°

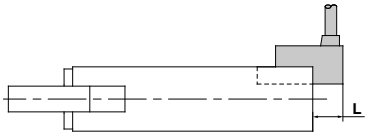
Protrusion of Auto Switch from Edge of Body

The projection of an auto switch from the edge of the body is shown in the table below. Use the table as a guideline for mounting.

Note) 2-color indicator type and perpendicular entry type protrude in the direction of the lead wire entry.



When auto switch D-M9□ is used



When auto switch D-M9□V is used

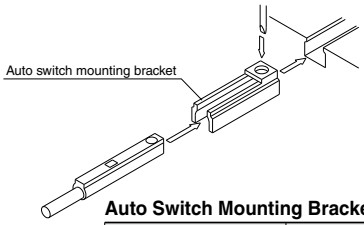
Max. Protrusion of Auto Switch from Edge of Body (L)

(mm)

Air gripper model	Finger position	Auto switch model: Protrusion In-line	Perpendicular	In-line	Perpendicular
		D-M9□ D-M9□W D-M9□A	D-M9□V D-M9□WV D-M9□AV	D-M9□A	D-M9□AV
MHY2-10D	Open	—	—	—	—
	Closed	3	1	5	3
MHY2-16D	Open	—	—	—	—
	Closed	3	1	5	3
MHY2-20D	Open	—	—	—	—
	Closed	—	—	3	1
MHY2-25D	Open	—	—	—	—
	Closed	—	—	1	—

Auto Switch Mounting

(1) Insert the auto switch bracket into the installation groove of the gripper as shown below and roughly set it.
(2) Insert the auto switch into the auto switch bracket installation groove.
(3) After confirming the detecting position, tighten the set screws (M2.5) attached to the auto switch and set it.
(4) Be sure to change the detecting position in the state of (2).



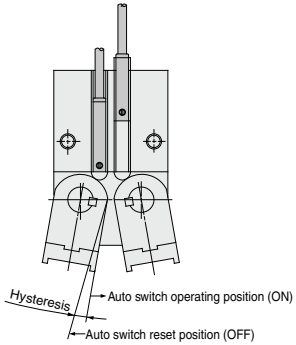
Auto Switch Mounting Bracket: Part No.

Auto switch part no.	Auto switch mounting bracket part no.
D-M9□(V)/M9□W(V)/M9□A(V)	BMG2-012

Note) Use a screwdriver with a grip diameter of 5 to 6 mm to tighten the set screws (M2.5). The tightening torque should be 0.5 to 1 N•m. As a rule, it should be turned about 90° beyond the point at which tightening can be felt.

Auto Switch Hysteresis

Auto switches have hysteresis similar to micro switches. Use the table below as a guide when adjusting auto switch positions, etc.

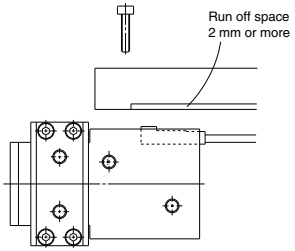


Air gripper model \ Auto switch model	D-Y59□/Y69□ D-Y7P(V)/Y7□W(V)
MHW2-20D	4°
MHW2-25D	4°
MHW2-32D	2°
MHW2-40D	2°
MHW2-50D	2°

Air gripper model \ Auto switch model	Max. hysteresis (Max. value) D-M9□(V) D-M9□W(V) D-M9□A(V)
MHW2-20D	4°
MHW2-25D	4°
MHW2-32D	2°
MHW2-40D	2°
MHW2-50D	2°

Handling of Mounting Brackets

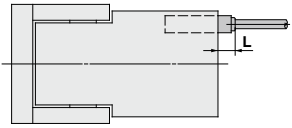
When auto switch is set on mounting side as shown below, allow at least 2 mm run off space on mounting late since the auto switch is protruded from the gripper edge.



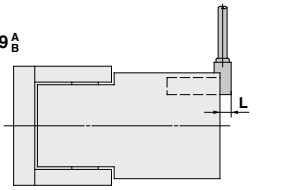
Protrusion of Auto Switch from Edge of Body

The maximum protrusion of an auto switch (when fingers are fully closed) from the edge of the body is shown in the table below. Use the table as a guideline for mounting.

When auto switches D-M9□/M9□W/Y59 A/B, D-M9□A, D-Y7□, Y7□W are used



When auto switches D-M9□V/M9□WV/Y69 A/B, D-M9□AV, D-Y7□V, Y7□WV are used



Max. Protrusion of Auto Switch from Edge of Body (L)

(mm)

Air gripper model	Finger position \ Auto switch model	Protrusion (mm) In-line electrical entry type D-Y59□/Y7P/Y7□W	Perpendicular electrial entry type D-Y69□/Y7PV/Y7□WV
MHW2-20D	Open	—	—
	Closed	7	5
MHW2-25D	Open	—	—
	Closed	7	5
MHW2-32D	Open	—	—
	Closed	4	2
MHW2-40D	Open	—	—
	Closed	3	1
MHW2-50D	Open	—	—
	Closed	1	—

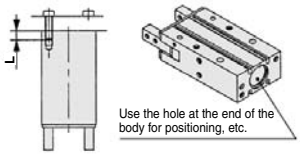
(mm)

Air gripper model	Finger position \ Auto switch model	Protrusion (mm) In-line electrical entry type D-M9□/M9□W	M9□A	Perpendicular electrial entry type D-M9□V/M9□WV	M9□AV
MHW2-20D	Open	—	—	—	—
	Closed	7	9	5	7
MHW2-25D	Open	—	—	—	—
	Closed	7	9	5	7
MHW2-32D	Open	—	—	—	—
	Closed	4	6	2	4
MHW2-40D	Open	—	—	—	—
	Closed	3	5	1	3
MHW2-50D	Open	—	—	—	—
	Closed	1	3	—	1

Mounting Air Grippers/Series MHY2

Possible to mount from 3 directions.

Axial Mounting (Body Tapped)

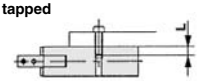


Model	Applicable bolts	Max. tightening torque (N·m)	Max. screw-in depth (Lmm)
MHY2-10D	M3 x 0.5	0.88	6
MHY2-16D	M4 x 0.7	2.1	8
MHY2-20D	M5 x 0.8	4.3	10
MHY2-25D	M6 x 1	7.4	12

Model	Bore(mm)	Hole depth (mm)
MHY2-10D	ø11H9 $^{+0.043}_{0}$	1.5
MHY2-16D	ø17H9 $^{+0.043}_{0}$	1.5
MHY2-20D	ø21H9 $^{+0.052}_{0}$	1.5
MHY2-25D	ø26H9 $^{+0.052}_{0}$	1.5

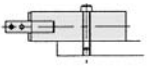
Lateral mounting (Body Tapped, Body through-hole)

●**Body tapped**



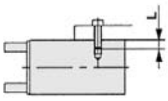
Model	Applicable bolts	Max. tightening torque (N·m)	Max. screw-in depth (Lmm)
MHY2-10D	M3 x 0.5	0.88	6
MHY2-16D	M4 x 0.7	2.1	8
MHY2-20D	M5 x 0.8	4.3	10
MHY2-25D	M6 x 1	7.4	12

●**Body through-hole**



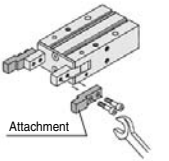
Model	Applicable bolts	Max. tightening torque (N·m)
MHY2-10D	M3 x 0.5	0.88
MHY2-16D	M4 x 0.7	2.1
MHY2-20D	M5 x 0.8	4.3
MHY2-25D	M6 x 1	7.4

Vertical Mounting (Body Tapped)



Model	Applicable bolts	Max. tightening torque (N·m)	Max. screw-in depth (Lmm)
MHY2-10D	M3 x 0.5	0.59	4
MHY2-16D	M4 x 0.7	1.3	5
MHY2-20D	M5 x 0.8	3.3	8
MHY2-25D	M6 x 1	5.9	10

How to Mount the Attachment to the Finger



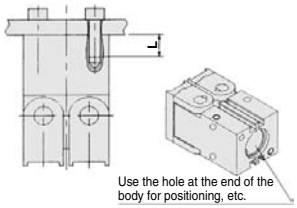
(1) To mount the attachment to the finger, make sure to use a wrench to support the attachment so as not to apply undue strain on the finger.
(2) Refer to the table below for the proper tightening torque on the bolt used for securing the attachment to the finger.

Model	Applicable bolts	Max. tightening torque (N·m)
MHY2-10D **MHY2-16D**	M3 x 0.5	0.59
MHY2-20D	M4 x 0.7	1.4
MHY2-25D	M5 x 0.8	2.8

Mounting Air Grippers/Series MHW2

Possible to mount from 3 directions.

Axial Mounting (Body Tapped)

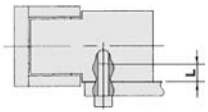


Model	Applicable bolts	Max. tightening torque (N·m)	Max. screw-in depth (Lmm)
MHW2-20D	M5 x 0.8	4.3	10
MHW2-25D	M6 x 1	7.4	12
MHW2-32D	M6 x 1	7.4	12
MHW2-40D	M8 x 1.25	17.7	15
MHW2-50D	M10 x 1.5	37.2	20

Model	Bore(mm)	Hole depth (mm)
MHW2-20D	ø21H9 $^{+0.052}_{0}$	3
MHW2-25D	ø26H9 $^{+0.052}_{0}$	3
MHW2-32D	ø34H9 $^{+0.062}_{0}$	4
MHW2-40D	ø42H9 $^{+0.062}_{0}$	4
MHW2-50D	ø52H9 $^{+0.074}_{0}$	5

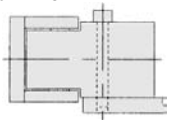
Lateral mounting (Body Tapped, Body through-hole)

●Body tapped



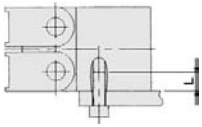
Model	Applicable bolts	Max. tightening torque (N·m)	Max. screw-in depth (Lmm)
MHW2-20D	M5 x 0.8	4.3	10
MHW2-25D	M6 x 1	7.4	12
MHW2-32D	M6 x 1	7.4	12
MHW2-40D	M8 x 1.25	17.7	16
MHW2-50D	M10 x 1.5	37.2	20

●Body through-hole



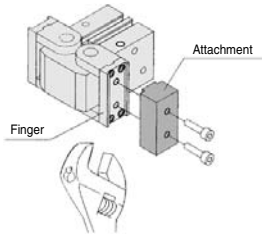
Model	Applicable bolts	Max. tightening torque (N·m)
MHW2-20D	M4 x 0.7	2.1
MHW2-25D	M5 x 0.8	4.3
MHW2-32D	M5 x 0.8	4.3
MHW2-40D	M6 x 1	7.4
MHW2-50D	M8 x 1.25	17.7

Vertical Mounting (Body Tapped)



Model	Applicable bolts	Max. tightening torque (N·m)	Max. screw-in depth (Lmm)
MHW2-20D	M5 x 0.8	2.9	7
MHW2-25D	M6 x 1	5.9	10
MHW2-32D	M6 x 1	5.9	10
MHW2-40D	M8 x 1.25	17.7	15
MHW2-50D	M10 x 1.5	37.2	20

How to Mount the Attachment to the Finger



(1) To mount the attachment to the finger, make sure to use a wrench to support the attachment so as not to apply undue strain on the finger.
(2) Refer to the table below for the proper tightening torque on the bolt used for securing the attachment to the finger.

Model	Applicable bolts	Max. tightening torque (N·m)
MHW2-20D	M4 x 0.7	1.4
MHW2-25D	M5 x 0.8	2.5
MHW2-32D	M6 x 1	4.1
MHW2-40D	M8 x 1.25	10.6
MHW2-50D	M10 x 1.5	24.5